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Fortuna, Miguel A ; Zaman, Luis ; Wagner, Andreas ; Bascompte, Jordi

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# Non-adaptive origins of evolutionary innovations increase network complexity in interacting digital organisms\*

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## Abstract

The origin of evolutionary innovations is a central problem in evolutionary biology. To what extent such innovations have adaptive or non-adaptive origins is hard to assess in real organisms. This limitation, however, can be overcome using digital organisms, i.e., self-replicating computer programs that mutate, evolve, and coevolve within a user-defined computational environment. Here we quantify the role of the non-adaptive origins of host resistance traits in determining the evolution of ecological interactions among host and parasite digital organisms. We find that host resistance traits arising spontaneously as exaptations increase the complexity of antagonistic host-parasite networks. Specifically, they lead to higher host phenotypic diversification, larger number of ecological interactions, and higher heterogeneity in interaction strengths. Given the potential of network architecture to affect network dynamics, such exaptations may increase the persistence of entire communities. Our “in silico” approach, therefore, may complement current theoretical advances aimed at disentangling the ecological and evolutionary mechanisms shaping species interaction networks.

Keywords: digital coevolution, ecological networks, host-parasite interactions, exaptation.

# 1 Introduction

2 It has recently been shown that interactions among coevolving species promote the emer-  
3 gence of evolutionary innovations, defined as qualitatively novel and beneficial traits.  
4 Among such innovations are host resistance traits for escaping parasites (Zaman *et al.*,  
5 2014) and the ability of parasites to infect either new (Duffy *et al.*, 2007; Elena, 2016) or  
6 current (Meyer *et al.*, 2012) hosts through novel pathways. Some of these studies have  
7 even identified the sequence of mutations leading to evolutionary innovation (e.g., Duffy  
8 *et al.*, 2007; Meyer *et al.*, 2012; Elena, 2016). In general, the larger the number of muta-  
9 tions required to evolve an innovation, the less likely is that this process takes place in a  
10 single step (e.g., Kuinen *et al.*, 2006). However, we still know little about the evolutionary  
11 origins—adaptive or non-adaptive—of such innovations, and whether they foster the role  
12 of coevolution in opening multiple paths to future innovation.

13 Palaeontologists Stephen J. Gould and Elisabeth S. Vrba (1982) introduced the con-  
14 cept of exaptations to refer to organismal traits that are either non-adaptive when they  
15 originate, or that were selected for a different function than the one currently performed.  
16 For example, the evolution of the genome complexity from prokaryotes to multicellular eu-  
17 karyotes might have non-adaptive origins (Lynch & Conery, 2003). This non-adaptationist  
18 theory is supported by the increase in genome entropy, which is inevitably triggered by  
19 reduction of population size—which in turn, strengthened the effects of random genetic  
20 drift and weaken the effects of purifying selection (Koonin, 2004). In fact, it has been  
21 shown that small and large populations are favored to evolved larger genomes, which  
22 provides the opportunity for subsequent increases in phenotypic complexity (Labar &  
23 Adami, 2016). More recently, experimental studies on promiscuous enzymes (O’Brien &  
24 Herschlag, 1999; Aharoni *et al.*, 2005) have emphasized the importance of exaptation in

1 evolution. These proteins can acquire new functions as byproducts of adaptations and  
2 thus help organisms survive in different environments. Similarly, recent work on metabolic  
3 networks has focused on how often adaptive metabolic traits have non-adaptive origins  
4 (Barve & Wagner, 2013; Notebaart *et al.*, 2014; Hosseini & Wagner, 2016). These stud-  
5 ies showed that bacteria viable on glucose as a sole carbon source can also be viable on  
6 multiple other carbon sources that were not targets of selection. This non-adaptive abil-  
7 ity of surviving in alternative carbon sources emerges as a byproduct of the complexity  
8 of biochemical reaction networks. Indeed, the complexity of metabolic networks can in-  
9 crease the potential for exaptations and, hence, can thus contribute to the pervasiveness  
10 of non-adaptive traits in biological systems (Barve & Wagner, 2013).

11 In artificial life systems, such as self-replicating and evolving computer programs—  
12 digital organisms—the ability of an organism to compute simple Boolean logic functions  
13 on binary numbers can emerge, likewise, as a byproduct of computing more complex  
14 functions. These genetically-encoded phenotypes result from the coordinated execution  
15 of “genetic building blocks” (i.e., computational instructions that organisms harbor in  
16 their genomes), which are analogous to developmental processes guided by regulatory  
17 programs in biology (Fortuna *et al.*, 2017). The higher the complexity of a function  
18 computed by a digital organism is, the greater is the likelihood that the organism can  
19 also compute simpler functions, i.e., the greater is the potential for exaptations.

20 If qualitatively novel and potentially beneficial traits arise spontaneously and non-  
21 adaptatively, regardless of any later adaptive function, the environment may determine  
22 how fast they become adaptive. On the one hand, biotic interactions might play an im-  
23 portant role in determining the benefit that a trait provides and help natural selection  
24 spread it through a population. Recent coevolutionary models have suggested that species  
25 interactions in complex networks change the mean value of the traits involved in the eco-

1 logical interactions among the partners (Guimarães *et al.*, 2011; Nuismer *et al.*, 2013;  
2 Andreazzi *et al.*, 2017), which influences evolutionary dynamics. On the other hand, a  
3 frequent non-adaptive origin of evolutionary innovations might drive species interactions  
4 and enhance the complexity of the entangled web of ecological interactions among organ-  
5 isms. Quantifying the role of exaptations in shaping species interaction networks requires  
6 a framework to discern exaptations from adaptations.

7       Disentangling non-adaptive from adaptive origins of evolutionary innovations in natu-  
8 ral ecological communities is so far unfeasible. In contrast, artificial life evolving systems—  
9 such as the digital organisms mentioned above—allow us to suppress mutations responsi-  
10 ble for non-adaptive origins of evolutionary innovations. Avida is a widely-used software  
11 platform for the study of evolution (see Wilke & Ofria, 2004) that has recently been  
12 extended to study host-parasite coevolution (Fortuna *et al.*, 2013; Zaman *et al.*, 2014).

13       Digital coevolution between hosts and parasites resembles the coevolutionary dy-  
14 namics among *Escherichia coli* and lambda phages (Fig. 1). On the one hand, bacteria  
15 must have receptors on their surface in order to import resources from their environment.  
16 On the other hand, phages must attach to those receptors in order to infect bacteria.  
17 Therefore, a trade-off exists between having receptors for obtaining nutrients and being  
18 susceptible to phages. Coevolutionary dynamics results from bacteria evolving phage re-  
19 sistance by changing their surface receptors, and phages countering resistance by altering  
20 their tail fibers to attach to the novel receptors (Meyer *et al.*, 2012). Analogously, digital  
21 hosts must compute logic operations to consume resources and thus replicate, but those  
22 traits leave them susceptible to infection by digital parasites. Here we use digital coevo-  
23 lution to shed light on the role of the non-adaptive origins of evolutionary innovations in  
24 shaping the web of life.

# 1 Methods

## 2 Digital evolution

3 Digital evolution is an applied branch of Artificial Life. In this evolutionary computation  
4 framework, self-replicating computer programs—digital organisms—evolve within a user-  
5 defined computational environment (Wilke & Adami, 2002). Avida is the most widely  
6 used software platform for research in digital evolution (Ofria & Wilke, 2004). It satisfies  
7 the three essential requirements for evolution to occur: replication, heritable variation,  
8 and differential fitness. Differences in fitness among digital organisms arise through com-  
9 petition for the limited resources of memory space and central processing unit (CPU)  
10 time. A digital organism in Avida consists of a sequence of instructions—its genome or  
11 genotype—and a virtual CPU, which executes these instructions. Some of these instruc-  
12 tions are involved in copying an organism’s genome, which is the only way the organism  
13 can pass on its genetic material to future generations. To reproduce, a digital organism  
14 must copy its genome instruction by instruction into a new region of memory. The copy-  
15 ing process occasionally introduces mutations including point mutations, insertions, and  
16 deletions. For example, a point mutation occurs when an instruction is copied incorrectly,  
17 and is instead replaced in the offspring genome by an instruction chosen at random (with  
18 a uniform distribution) from a set of 33 possible instructions. In addition to the instruc-  
19 tions required for replication (i.e., viability), the instruction set includes basic arithmetic  
20 operations (such as addition, multiplications, and bit-shifts) as well as the logic operator  
21 *nand* that are executed on binary numbers taken from the environment through input-  
22 output instructions. When the output of processing these numbers equals the result of a  
23 specific Boolean logic operation, such as the AND and OR Boolean functions, the digital  
24 organism is said to have a trait represented by that logic operation. We have focused

1 here on the following 9 Boolean logic operations that organisms can perform on 32-bit  
2 one- and two-input numbers: NOT, NAND (not-and), AND, OR\_N (or-not), OR, AND\_N  
3 (and-not), NOR (not-or), XOR (exclusive or), and EQU (logical equality).

4 We configured the environment so that it contains a single resource that must be  
5 consumed by organisms for successful replication. This resource renews at a constant  
6 rate and influences the carrying capacity of the population. For organisms to successfully  
7 consume a unit of resource, they must compute before replication, at least one Boolean  
8 logic function. If there is no single available unit of this resource, replication fails and  
9 the organism begins the execution of its genome's instructions again without producing  
10 any offspring. When applied to multiple organisms, this procedure leads to density-  
11 dependent population growth. In addition, there are two sources of density-dependent  
12 mortality: 1) if an organism does not successfully divide, it dies after executing 5 times  
13 its genome's instructions (i.e., 5 failed replication attempts); and 2) as a result of offspring  
14 being randomly placed in the population, a resident organism can be overwritten by the  
15 newly generated offspring.

## 16 **Digital coevolution**

17 In order to study coevolution in populations of interacting organisms, we have imple-  
18 mented parasitic organisms and a mechanism for them to infect the above described  
19 digital organisms (i.e., hosts) based on genetically encoded phenotypes (Zaman *et al.*,  
20 2011; 2014). This new branch of Avida supports threading capabilities (i.e., more than  
21 one type of organism executing their instructions in parallel) and separate memory spaces  
22 for hosts and parasites (i.e., regions of memory reserved for the genome of the offspring  
23 produced during the self-replication process). It uses a 33-instruction set that expanded  
24 the 26-instruction default genetic language of Avida (Supplementary File 1).



1       Parasitic digital organisms are almost identical to the hosts, and as such they self-  
2 replicate by copying their genome instruction-by-instruction into a new memory space.  
3 But they operate inside hosts, stealing CPU cycles from them to execute their own  
4 genome’s instructions and, hence, reduce their host fitness. However, parasites have mem-  
5 ory spaces entirely separated from their host’s and, therefore, do not have access to their  
6 host’s instructions. This avoids any unforeseen side-effects such as those observed in the  
7 digital evolution platform Tierra (Ray, 1991), where parasites can overwrite their host’s  
8 genome. The selective pressure of a parasite on its host (i.e., virulence) is determined by  
9 the probability that a CPU cycle from the host will be given to the parasite. When this  
10 probability is set to 0.5, parasites and hosts split CPU cycles evenly, and when it is set  
11 to 1, the parasite uses all of its host’s CPU cycles. In the latter case, the relationship is  
12 analogous to a predator-prey interaction. After making a copy of its genome using the  
13 CPU cycles “stolen” from its host, a parasite must place its newly generated offspring  
14 into an uninfected host. It attempts to do this by executing the instruction “Inject”. The  
15 parasite’s offspring is then randomly placed in the host population. If the chosen memory  
16 space is occupied by an uninfected host, the parasite can infect it. In contrast, if the  
17 memory space is either occupied by an infected host or empty, infection will fail. Multiple  
18 infections are not allowed (i.e., a host can only be infected by one parasite).

19       Parasites can not infect just any host. The mechanism of infection is based on phe-  
20 notypic trait matching, i.e., an uninfected host will be infected by a parasite’s offspring  
21 if the parasite computed at least one of the Boolean logic functions that the host also  
22 computed. This mechanism of infection emulates the inverse gene-for-gene model, where  
23 infectiousness is determined by parasite recognition of host signals and/or receptors (Fen-  
24 ton *et al.*, 2009). Parasites, like hosts, show density-dependent population growth (i.e.,  
25 infections fail when most hosts are already infected). In addition, a parasite dies when

1 its host replicates successfully.

## 2 **Coevolutionary dynamics**

3 We sampled genotype space to find the hosts and parasites that were used as ances-  
4 tors in the coevolutionary scenarios described below. Specifically, we first identified 30  
5 mutationally-robust viable hosts capable of performing only the NOT logic operation  
6 and 15 mutationally-robust viable parasites capable of performing only the NOT logic  
7 operation. Next, we quantified the long-term stable coexistence of all  $30 \times 15 = 450$   
8 host-parasite pairs in a purely ecological scenario where mutations were allowed neither  
9 in hosts, nor in parasites. We kept the 216 (48%) host-parasite pairs where both hosts and  
10 parasites coexisted to study their coevolutionary dynamics (see Supporting Information).

11 Then, we expanded this purely ecological framework by introducing evolution into  
12 host-parasite population dynamics. We introduced novel genotypic variation into the host  
13 and parasite populations as single-point mutations, i.e., substitutions of one instruction  
14 in the offspring's genome by another instruction randomly chosen from the 33-instruction  
15 set. Hence, genome size was kept constant for both hosts and parasites. We applied a  
16 mutation rate per instruction in an organism's genome of  $\mu_H = 0.025$  and  $\mu_P = 0.01$  for  
17 hosts and parasites, respectively. This means that, on average, 1 out of 40 host offspring  
18 will become a novel host, and 1 out of 100 parasite offspring will become a novel parasite.  
19 Note that in nature, mutation rates of phages are higher than those of bacteria but their  
20 genomes are also smaller, while here, genome size was the same and kept constant during  
21 the evolutionary processes for both hosts and parasites. We set the probability that a  
22 CPU cycle from an infected host was given to the parasite to 0.9 (i.e., the parasite used  
23 90% of the host CPU cycles).

24 For each of the 216 host-parasite pairs that coexisted in the long term in a purely

ecological scenario (Supplementary File 2), we performed 10 independent coevolutionary processes (i.e., replicates). Note that both host and parasite ancestors were able to compute the Boolean logic function NOT. Each process started from a population of  $10^4$  hosts with the same ancestral genotype and, after the host reached its carrying capacity ( $K \approx 6500$ , on average for the 30 distinct hosts used), we infected half of the host population with the same ancestral parasite genotype. After  $2 \times 10^5$  updates, where an update is the amount of time during which an organism executes on average 30 instructions (i.e., on average  $10^4$  generations), we stopped the coevolutionary process and retrieved the data generated during the entire process. We repeated each coevolutionary process for each of the two scenarios described below, i.e., allowing and prohibiting non-adaptive origins of resistance traits ( $216 \times 10 \times 2 = 4320$  coevolutionary processes).

### **Non-adaptive and adaptive origins of resistance traits**

As a host population evolves, organisms might perform other Boolean logic operations besides or instead of NOT. Performing a new logic function is analogous to evolving a novel trait. In order to become resistant, hosts must lose their ability to perform the ancestral NOT logic function (so that parasites cannot infect them) while also evolving a novel trait (i.e., the ability to perform a new Boolean logic function) so that they can continue to collect the resources required for replication. If a host evolves a novel logic function without losing the ancestral one, the novel function has no adaptive value, since the parasite can still infect the host, and since there is no fitness advantage in having more the one trait for collecting resources. Later on, when a host loses the ability to perform the ancestral logic function, the evolved trait will have an adaptive value since it has become necessary to collect resources. We then refer to this evolved trait as an exaptation—an adaptive trait of an organism that was not adaptive when it originated or we say that

1 this adaptation has a non-adaptive origin. In contrast to the scenario described next, we  
2 allow the replication of hosts capable of performing a novel logic function while keeping  
3 the ability to perform the ancestral one (Supplementary File 3).

4 When a host evolves a novel logic function while losing its ability to perform the  
5 ancestral one, the novel trait has adaptive value from its inception. This is so because  
6 it allows the host to collect resources required for replication and confers resistance to  
7 parasites. We suppress exaptations in this scenario by preventing the replication of hosts  
8 that perform more than one logic function (Supplementary File 4). Novel traits evolve at  
9 the same time that hosts lose ancestral traits. This means that a single-point mutation  
10 is responsible for both acquiring the novel function and losing the ancestral one. By pre-  
11 venting the replication of hosts having more than one trait we might bias the evolutionary  
12 trajectories that the host population could follow. However, this represents only 3.67%  
13 of the population (i.e.,  $\approx 239$  organisms in a population of  $\approx 6500$  hosts). Moreover,  
14 the fraction of the 1-mutant neighbors that are non-viable (i.e., they have genomes that  
15 do not allow them to produce offsprings) is smaller when traits have also non-adaptive  
16 origins (28%) than when they have only adaptive origins (31%; see Supplementary Fig-  
17 ure 1). This reduction in host population abundance introduced by new mutations is 10  
18 orders of magnitude larger than the 3.67% decrease in host population size artificially in-  
19 duced by our experimental design when traits have only adaptive origins (i.e., preventing  
20 the replication of hosts having more than one trait). Therefore, the slowing down in the  
21 host evolutionary potential when traits have only adaptive origins comes naturally from  
22 the coevolutionary process and not as much from our experimental procedure to prevent  
23 exaptations.

# Results

Evolutionary innovations that emerged as exaptations—adaptive traits that were not adaptive when they originated—influenced the coevolutionary dynamics among host and parasite digital organisms (see Fig. 2). Specifically, they altered the following ecological and evolutionary responses: 1) the likelihood for hosts to escape from parasites; 2) population abundances; 3) the evolution of host resistance traits; and 4) the complexity of the network of interactions among hosts and parasites.

## Exaptations and the likelihood of hosts escaping parasites

We observed coexistence of hosts and parasites during the entire coevolutionary process in both scenarios, namely, when resistance traits had both adaptive and non-adaptive origins vs when they had only adaptive origins. Specifically, for 90% of the 216 host-parasite pairs used as ancestors of the coevolutionary processes, host and parasite populations survived in the long-term. Parasites did not drive host extinction during any coevolutionary process. In contrast, hosts escaped from parasites—driving them to extinction—more frequently when resistance traits had both adaptive and non-adaptive origins than when they had only adaptive origins (it happened in at least one coevolutionary process for 84% and 76% of the 216 host-parasite pairs used as ancestors, respectively). That is, when resistance traits have non-adaptive origins, it is more likely for hosts to escape from parasites ( $\chi^2 = 3.72$ ,  $df = 1$ ,  $p = 0.027$ ; two-sample test for equal proportions).

## Exaptations and population abundance

Interestingly, the fraction of infected hosts—averaged over the entire coevolutionary process and over replicates where hosts and parasites coexisted—was 4% higher when the traits had a non-adaptive origin than when they had to have adaptive value from their in-

1 ception ( $t = 5.51$ ,  $df = 192$ ,  $p < 0.001$ ; paired t-test). This result contrasts with observed  
2 patterns in population abundance. Indeed, host and parasite population abundances—  
3 averaged in the same way—were 15% and 18% higher, respectively, when resistance traits  
4 had non-adaptive origins ( $t = 15.88$ ,  $df = 192$ ,  $p < 0.001$ , and  $t = 17.87$ ,  $df = 192$ ,  
5  $p < 0.001$ , respectively; paired t-test; Fig. 3a-b).

## 6 **Exaptations and the evolution of host resistance traits**

7 The maximum number of Boolean logic functions (i.e, potentially beneficial traits) evolved  
8 by hosts across all coevolutionary processes where they coexisted with the parasites was  
9 7 (out of 9, which is the maximum number of traits), regardless of the adaptive origin of  
10 those traits. However, when we compared the maximum number of novel traits evolved  
11 by hosts initiated from the same host-parasite pair in both scenarios, we found a highly  
12 significant 23% increase in the number of evolved traits with non-adaptive origin ( $t = 7.05$ ,  
13  $df = 192$ ,  $p < 0.001$ ; paired t-test). That is, the non-adaptive origin of resistance traits  
14 promotes host phenotypic diversification (Fig. 3c).

## 15 **Exaptations and the complexity of host-parasite networks**

16 The number of interactions between single-trait host phenotypes and parasite phenotypes  
17 (i.e., pairwise infections)—averaged over the entire coevolutionary process and over repli-  
18 cate where hosts and parasites coexisted—was twice as high when the traits had also  
19 non-adaptive origins ( $t = 10.91$ ,  $df = 192$ ,  $p < 0.001$ ; Fig. 3d). Beyond the number of  
20 ecological interactions, we calculated interaction evenness (Bersier *et al.*, 2002). It mea-  
21 sures how equifrequently distributed interaction strengths are among hosts and parasites  
22 (accounting for differences in the number of interactions). Interaction strengths are esti-  
23 mated as the fraction of hosts with a given phenotype that is infected by each parasite

1 phenotype. The opposite of this measure gives an idea of the heterogeneity in the distri-  
2 bution of interaction strengths across links. Such heterogeneity in interaction strengths  
3 was higher (i.e., interaction evenness was 6% lower) when traits were allowed to have  
4 non-adaptive origins than when they have only adaptive origins ( $t = -2.97$ ,  $df = 192$ ,  
5  $p = 0.002$ ; Fig. 3e).

## 6 Discussion

7 We have shown that the non-adaptive origins of host resistance traits facilitate hosts  
8 escaping from parasites and promote host phenotypic diversification. This ability of  
9 hosts to acquire qualitatively novel and beneficial functions (i.e., evolutionary innova-  
10 tions) enables parasites to expand their ecological opportunities. As a result, the role of  
11 evolutionary innovations extends beyond the pairwise realm to entire networks of interac-  
12 tions. Specifically, we have shown that exaptations promote the complexity of antagonistic  
13 host-parasite networks by increasing the number of interactions among host and parasite  
14 phenotypes and the heterogeneity across interaction strengths.

15 In a previous study we have shown that potential exaptations appear spontaneously in  
16 evolving digital organisms and help bridge mutationally-connected networks of genotypes  
17 having the same phenotype (i.e., genotype networks; see Fortuna *et al.*, 2017). This high  
18 prevalence of exaptations suggests that the likelihood for a population to reach a novel  
19 trait  $j$  from organisms having trait  $i$  ( $p_{i \rightarrow j}$ ) might be greater if the population encounters  
20 trait  $j$  first as an exaptation (i.e., organisms can have both traits at the same time) than  
21 finding directly the novel trait  $j$  (i.e.,  $p_{i \rightarrow ij} \times p_{ij \rightarrow j} > p_{i \rightarrow j}$ ). This could explain why the  
22 non-adaptive origins of evolutionary innovations facilitates hosts escape from parasites.

23 The presence of exaptations increases population abundances for both hosts and  
24 parasites, which can make the entire host-parasite network more robust to stochastic

1 fluctuations. A potential mechanism that might explain why the abundance of the host  
2 population is larger when resistance traits have adaptive and non-adaptive origins than  
3 when they have only adaptive origins relies on the characteristics of the regions of the  
4 genotype space occupied by the evolving host populations in both scenarios. When exap-  
5 tations are allowed, the host population move towards a more robust region of genotype  
6 space (i.e., the fraction of the 1-mutant neighbors having the same phenotype as the tar-  
7 get organism is larger when traits have also non-adaptive origins than when they have  
8 only adaptive origins; see Supplementary Figure 1).

9 Exaptations seem also to affect network robustness through their effect on our two  
10 measures of network architecture. First, the additional number of links resulting from the  
11 non-adaptive origins of innovations results in more connected networks. Such networks  
12 generally are more robust to species extinctions (Dunne *et al.*, 2002). Second, the increase  
13 in the heterogeneity of the distribution of interaction strengths resembles patterns in food  
14 webs and mutualistic networks, which contain a few strong interactions embedded within  
15 a matrix of weak interactions (Paine, 1992; Fagan & Hurd, 1994; Raffaelli & Hall, 1995;  
16 Wootton, 1997; Bascompte *et al.*, 2005; 2006). This heterogeneity has also been found to  
17 increase network stability (McCann *et al.*, 1998; Kokkoris *et al.*, 1999; Neutel *et al.*, 2002;  
18 Bascompte *et al.*, 2005; 2006).

19 One can perceive the patterns in network architecture reported above as an evo-  
20 lutionary innovation that increases network persistence. Thus, the direct evolutionary  
21 innovations at the scale of novel species interactions mediated through exaptations can  
22 scale up to generate a novel type of innovation, that of network structures that mediates  
23 the persistence of entire networks. Interaction networks shaped by exaptations, thus,  
24 should be view as coevolved structures that can not be reduced to the simple addition of  
25 the constituent pairwise interactions.



1        Network research has emphasised that understanding the relationships between pairs  
2 of species is not enough to understand the coexistence and functioning of entire networks.  
3 Our results show that coevolutionary processes may increase the number of opportunities  
4 leading to innovations of non-adaptive origin, which generates more complex networks.  
5 Coevolution, therefore, seems to be relevant for understanding the mechanisms shaping  
6 the complex web of life (Guimarães *et al.*, 2011; Nuismer *et al.*, 2013). Our results on  
7 the role of exaptations for ecological communities are also in line with Prigogine’s ideas  
8 of self-organization, by which innovations occur stochastically and are integrated into a  
9 system by deterministic relationships existing at the time (Prigogine, 1980).

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## **Data accessibility.**

Data are available in the Supporting Information.

## **Author contributions.**

Conceived and designed the experiments: MAF, JB, and AW.

Performed the experiments: MAF.

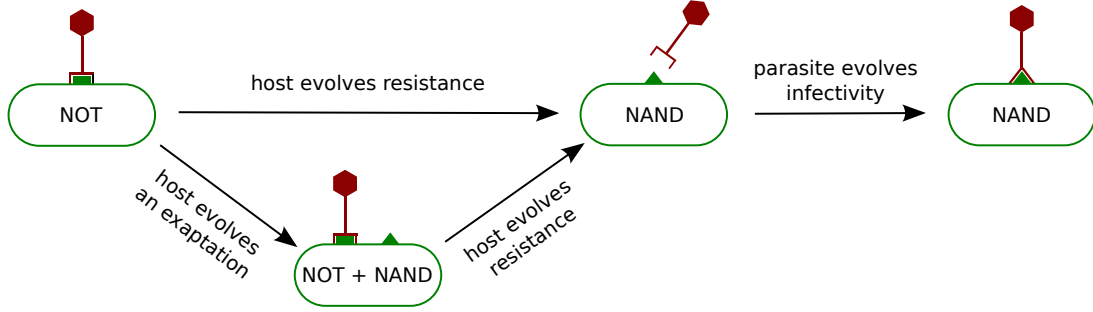
Analyzed the data: MAF.

Contributed reagents/materials/analysis tools: LZ.

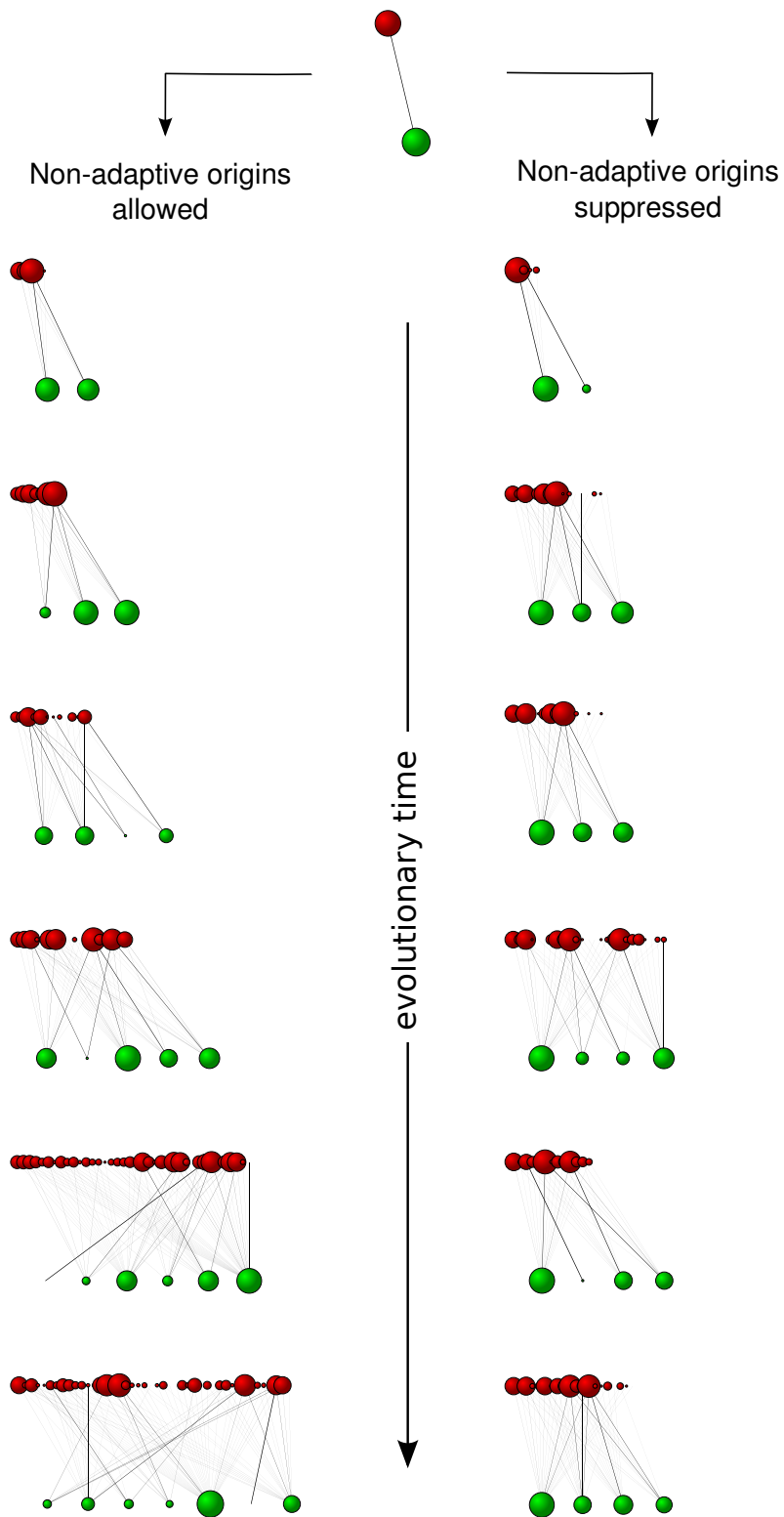
Wrote the manuscript: MAF, LZ, JB, and AW.

## **Competing interests**

The authors declare no competing interests.

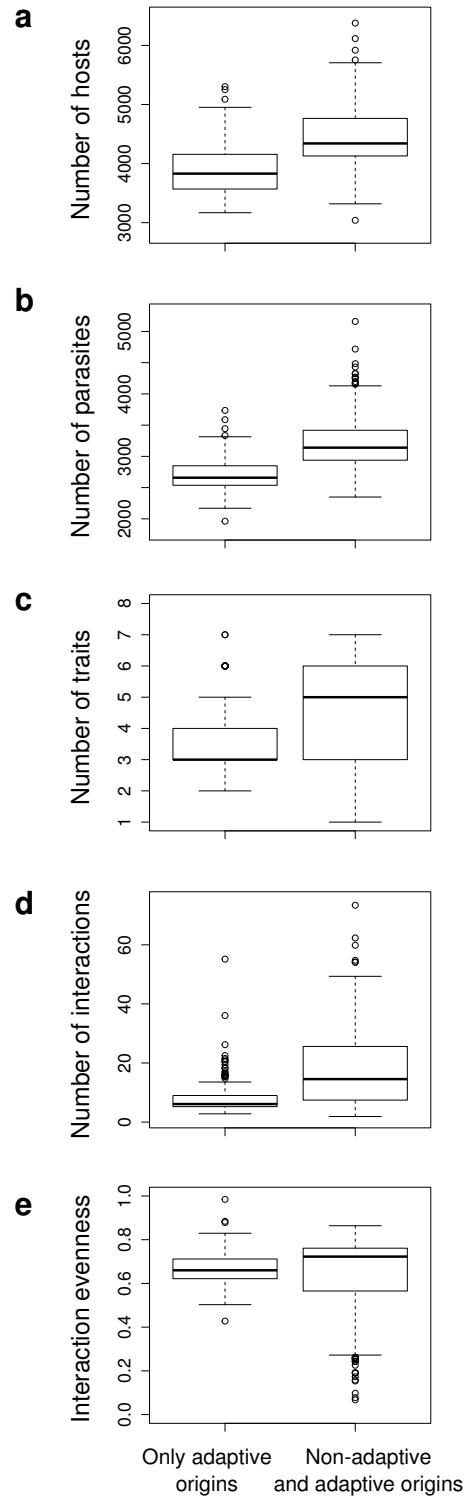


**Figure 1: Schematic representation of the adaptive and non-adaptive origins of a host resistance trait.** The host (green ellipse) has a receptor on its surface (i.e., a trait represented by a green rectangle) which allows it to consume resources from the environment. That receptor is also used by a parasite (in red) to infect the host. Computing logic functions, such as NOT and NAND, by executing the instructions that both digital hosts and parasites harbor in their genomes is analogous to having resistance and infectivity traits. The host can evolve a resistance trait (i.e., computing a novel Boolean logic operation such as NAND, represented by a green triangle on the surface of the host) following two different evolutionary trajectories: 1) evolving the novel trait through a single-point mutation while losing the ancestral one (i.e., computing the NAND logic function while losing the ability to perform the NOT logic function); or 2) evolving a non-adaptive trait (i.e., exaptation) through a single-point mutation that does not confer resistance to the host but facilitates the loss of the ancestral trait through a second mutation and, hence, provides resistance to the parasite. In this study, we compare a scenario with both possibilities (adaptive and non-adaptive) versus a second scenario where we suppress non-adaptive origins. The difference between the two scenarios will help us estimate the importance of non-adaptive origins of evolutionary innovations. After either resistance was evolved, the parasite may overcome it by mutations in its own genome and become infective again.





**Figure 2: Evolving interaction networks among digital host and parasite phenotypes in two contrasting scenarios: (i) when resistance traits have both adaptive and non-adaptive origins (left), and (ii) when resistance traits have only adaptive origins (right).** A phenotype (depicted as either a green or red node for hosts and parasites, respectively) is defined by a unique combination of Boolean logic functions (i.e., traits) that organisms with that phenotype compute. Starting from the same ancestral host and parasite phenotypes (represented at the top), the diversification of host resistance traits as well as who infects whom (depicted by the links connecting the nodes) are tracked over evolutionary time. The width of each link (i.e., interaction strength) is proportional to the fraction of organisms having a particular host phenotype infected by parasites encoding a given phenotype. The size of the nodes is proportional (in logarithmic scale) to the number of organisms having a particular phenotype. Each network depicts host-parasite interactions recorded at a specific point in evolutionary time (equal time for both right and left boxes placed at the same height). Only single-trait host phenotypes were allowed to evolve when traits had only adaptive origins. For traits with also non-adaptive origins, only single-trait hosts are represented. Parasite phenotypes can have more than one trait in both scenarios.



**Figure 3: Ecological and evolutionary consequences of the non-adaptive origins of host resistance traits.** The number of hosts (a), parasites (b), traits in the host population (c) and interactions of single-trait hosts (d), were higher when resistance traits have both adaptive and non-adaptive origins than when the traits have only adaptive origins. On the contrary, interaction evenness (i.e., how well distributed the interaction strengths are among hosts and parasites accounting for differences in the number of interactions) was lower when resistance traits have both adaptive and non-adaptive origins than when the traits have only adaptive origins (e). Median (n=193 coevolutionary processes among host and parasite phenotypes) and upper and lower quartiles are shown.

# Supporting Information

## Sampling genotype space

We first generated 50 viable organisms by selecting random genomes with 100 instructions, where we chose each instruction in a genome randomly and uniformly among a set of 32 instructions out of the 33-instruction alphabet (Supplementary File 5). We excluded the “Inject” instruction from the instruction set at this stage because this instruction is only used by parasites to infect hosts, and hence, it does not play any role in the process of generating organisms that will become hosts. Finding those 50 organisms required us to sample  $\approx 10^{11}$  random sequences. These 50 organisms were only capable of self-replication and did not perform any Boolean logic operation (i.e., they were merely viable organisms; Supplementary File 6).

In a second step, we aimed to find organisms capable of performing the NOT logic operation. To this end, for each of those merely viable organisms we performed 50 random walks through the genotype space. Each step in each random walk mutated one randomly chosen instruction in the random-walking genotype, and replaced it with a randomly-chosen instruction from the 32-instruction set mentioned above. Whenever such a mutation produced a non-viable organism or an organism capable of performing any logic function distinct from NOT, we reverted the mutation and mutated a new, randomly chosen instruction. We repeated this procedure until a viable organism capable of performing the NOT logic function appeared (Supplementary File 7).

Finally, to increase the robustness of those single-trait organisms, we performed a purifying selection process that moved organisms away from the merely-viable set of genotypes. That is, for each organism we started an evolutionary process in the standard mode of Avida from a population consisting of  $10^4$  organisms having the previously encountered

1 genotype. This process neither imposed selection for reducing the number of executed  
2 instructions required to produce an offspring (i.e., generation time) nor for performing  
3 any Boolean logic operations. Only organisms performing the NOT logic operation were  
4 allowed to replicate and their offspring differed in a single randomly chosen instruction  
5 from the genotype of its parent. After  $10^5$  updates, where an update is the amount of time  
6 during which an organism executes on average 30 instructions, we stopped the evolution-  
7 ary process and kept only one randomly chosen genotype per population. By imposing  
8 this high rate of mutations, we evolved organisms with large robustness (Wilke *et al.*,  
9 2001). In summary, our sampling of the genotype space found 50 mutationally-robust  
10 viable organisms capable of performing the NOT logic operation (Supplementary File 8).

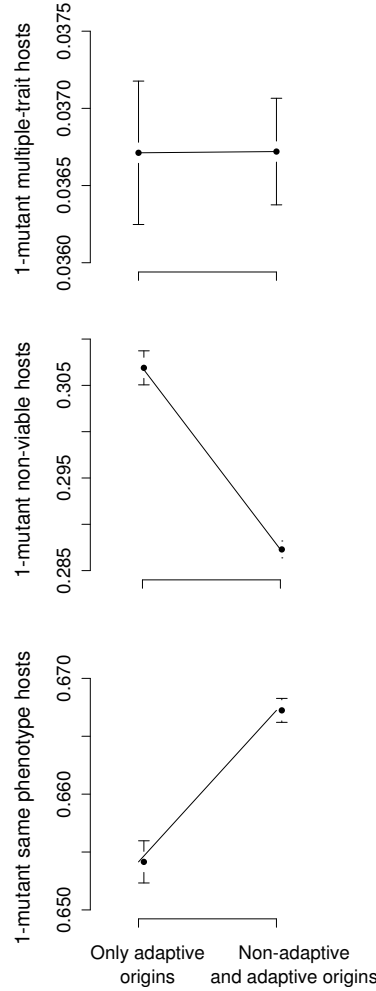
## 11 **Searching for host and parasite ancestors**

12 A parasite must replicate faster than its host, otherwise it will die when the host replicates.  
13 Then, we took the 25 organisms with the longest generation times as hosts. After that,  
14 we replaced the instruction “Divide-Erase” (i.e, the instruction that splits the organism’s  
15 offspring from its parent and places it in a new memory space) by the instruction “Inject”  
16 (i.e., the instruction that the parasite uses to place its offspring into a host) from the  
17 genomes of the remaining 25 organisms. This is a simple way to convert an organism into  
18 a parasite. But the viability of a parasite depends on the host as well, since the parasite  
19 must replicate after the host has performed the logic operation NOT in order to be able  
20 to infect it. We tested the viability of those 25 parasites by observing their ability to  
21 replicate and infect each of the 25 hosts in the standar mode of Avida. Only 15 parasites  
22 were able to replicate and infect at least one of the 25 hosts (Supplementary File 9).  
23 None of the 5 parasites with the longest generation times were viable on any of those 25  
24 hosts. We took those 5 parasites and replaced the instruction “Inject” by the instruction

1 “Divide-Erase” to revert them into hosts again, and added them to our previous set of  
2 hosts, which finally comprises a total number of 30 hosts (Supplementary File 10).

3 In the next step, we quantified the long-term stable coexistence of all  $30 \times 15 = 450$   
4 host-parasite pairs in a purely ecological scenario. That is, we performed 450 ecological  
5 processes in the standard mode of Avida where mutations were allowed neither in hosts,  
6 nor in parasites. Each process started from a population of  $10^4$  single-genotype hosts and,  
7 after the host reached its carrying capacity ( $K \approx 6500$ , on average for the 30 hosts, after  
8 1000 updates) we infected half of the host population with the same ancestral parasite  
9 genotype. Then, we computed the number of host-parasite population pairs where both  
10 hosts and parasites coexisted after  $10^4$  updates. Only 166 (37%) host-parasite population  
11 pairs coexisted when the parasite virulence was set to 0.75. This number increased to  
12 216 (48%) pairs when virulence was 0.90. We used those 216 host-parasite pairs as the  
13 ancestors of the evolutionary processes analyzed in this study (Supplementary File 2).

## Supplementary Figures



**Supplementary Figure 1: Analysis of the 1-mutant neighborhood of host populations.** We computed the fraction of the  $32 \times 100 = 3200$  1-mutant neighbors that are i) non-viable, ii) viable and have the same phenotype than the parent organism, and iii) viable and have a novel phenotype consisting of more than one trait, for each host at different time steps (data pooled together) and for each scenario (i.e, when traits had both adaptive and non-adaptive origins, and when they had only adaptive origins).

## Supplementary Files

**S1 File.** 33-instruction set.

**S2 File.** Host-parasite pairs used as ancestors.

**S3 File.** Configuration of the non-adaptive and adaptive scenario.

**S4 File.** Configuration of the adaptive scenario.

**S5 File.** 32-instruction set.

**S6 File.** Merely-viable organisms.

**S7 File.** Viable organisms capable of computing the NOT logic function.

**S8 File.** Viable and mutationally-robust organisms capable of computing the NOT logic function.

**S9 File.** Parasites.

**S10 File.** Hosts.